

NAME

set_lm – set lower and upper software limits

SYNOPSIS

```
set_lm motor low_limit high_limit
```

DESCRIPTION

The `set_lm` macro is used to establish the *low_limit* and *high_limit* for one *motor* in units of the user positions. (The built-in function `set_lim()`, used by the `set_lm` macro, establishes the limits in terms of dial positions.)

EXAMPLE

```
set_lm phi -90 90
```

SEE ALSO

lm